

KR05 – Data Collection and Edge Processing

SCOPE

7SHIELD UAV is one of the first UAVs with a separate onboard computer with an embedded Jetson Xavier processor, running the latest version of Robot Operating System (ROS) in order to host Artificial Intelligence (AI) algorithms for object detection and identification for edge processing.

DCEP is embedding the 7SHIELD Object Detection (ODE) and interfacing with the control room provided by 7SHIELD in order to **detect physical threats**.





The embedded pc on which DCEP is installed

PARTNERS

A

ACCELIGENC

Cyprus



In particular, the company, since its establishment, started focalising its R&D activities on robotic systems and subsystems such as UAVs.

design

and

PURPOSE

Collection and The **Data** Edge Processing (DCEP) is a component including the Unmanned Aerial Vehicle (UAV) that embeds an edge processor able to host advanced AI algorithms to support object detection and identification services (on board processing).

Furthermore, this component provides all communication capabilities with the control room as well as the handling of basic drone functions such as flights. autonomous camera synchronization and locating objects during the flight.

STAKEHOLDERS

With its Autonomous UAVs equipped with embedding artificial intelligence, ACCELI is targeting the market segments listed below:

- Critical Infrastructure Operators
- Civil Protection
- Agriculture

The advantage of this module is that it is fully adaptable on any requirement or climate based on the needs of the operators.

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TECHNOLOGY

ACCELI exploits the features of rapid prototyping through the use of 3D printing and Computerized Numerical **Control Machine** (CNC) for the manufacturing of 7SHIELD UAV.

7SHIELD Mission UAV is capable to perform on-board image processing, making use of machine learning-based techniques, and more precisely Deep Neural Networks (DeepNN) and Convolutional Neural Networks (CNN) exploiting the data (e.g., 2D/ 3D images/ point clouds) obtained from the various aforementioned sensory inputs.

The innovation of DCEP development lies on the installation, integration and deployment of an GPU in the UAV flying system.

FUTURE IMPROVEMENTS

There are two areas of improvement:

- 1. Fully autonomous operation. The UAV will be operated after receiving an alert by the control room or the field sensors.
- 2. Power consumption efficiency. The use of alternative battery technology or the deployment of chargers pods on the field.

www.7shield.eu

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All the modules developed in the frame of 7SHIELD have been designed with the consultancy of identified the **requirements** provided by the partners working in the space sector acting as Pilots, who provided the Critical Infrastructures for testing and demonstration.

leads

the

a fully customized Mission UAV, able to

accommodate the various hardware

components (e.g., height/ distance

sensors, cameras) in order to execute

smart algorithms (e.g., visual object

detection and collision avoidance

services, algorithms for swarming), and

generally to be easily adapted to the

current operation by the user.

CONTACTS